

# Synthetic corruption of images for anomaly detection using autoencoders

[ISPG SEMINAR]

Anne-Sophie COLLIN

Supervisor

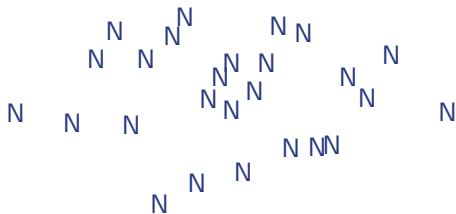
Christophe DE VLEESCHOUWER

3<sup>rd</sup> of JUNE 2020

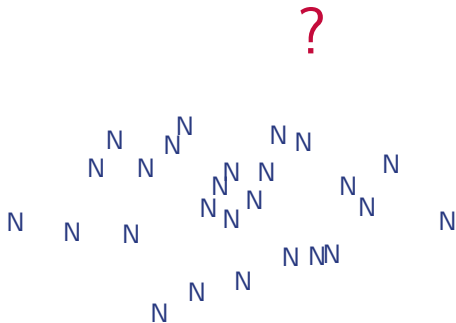
# Anomaly Detection

N

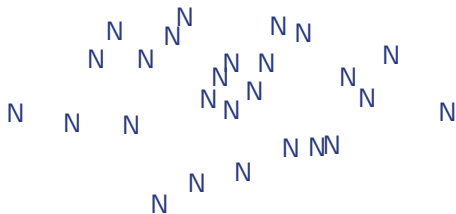
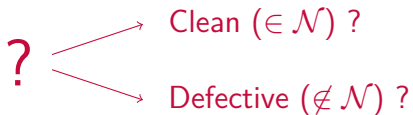
# Anomaly Detection



# Anomaly Detection



# Anomaly Detection



Clean



Clean



Defective



Clean



Defective



Clean



Clean



Defective



Clean



Clean



Defective



Clean



Clean



Clean



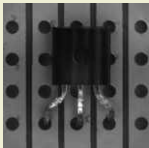
Defective



Defective



Clean



Clean



Clean



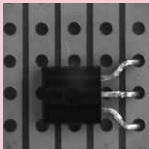
Clean



Clean



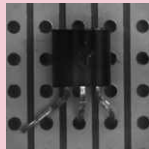
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Clean



Defective



Defective



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Clean



Clean



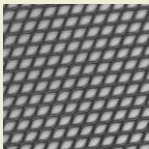
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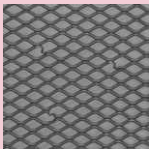
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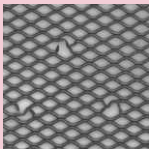
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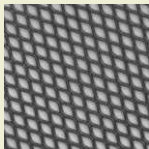
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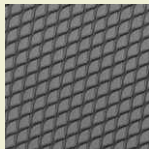
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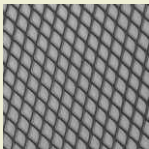
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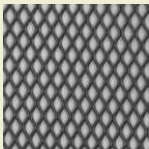
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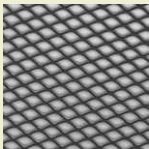
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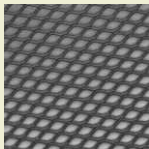
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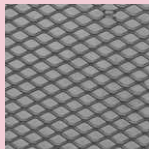
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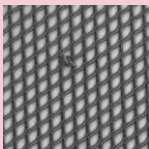
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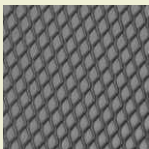
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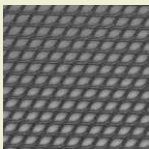
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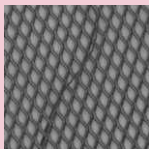
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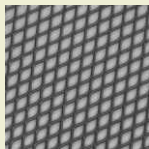
Clean



Defective



Clean





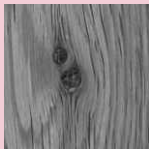
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Clean



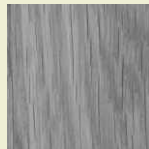
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Defective



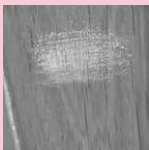
Clean



Clean



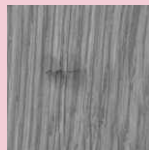
Defective



Clean



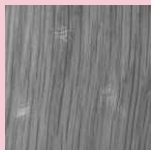
Defective



Defective



Defective



Clean



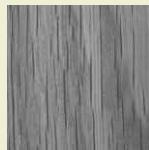
Defective



Clean



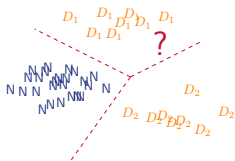
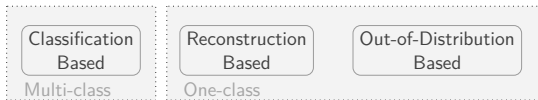
Clean



# Approaches

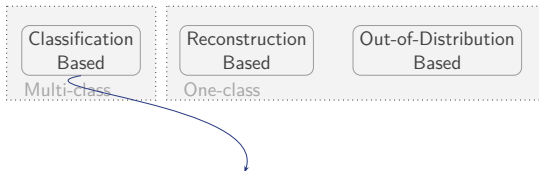


# Approaches



$$p(? \in \mathcal{N}) > p(? \in \mathcal{D}_i)$$

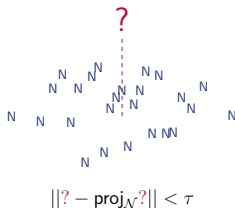
# Approaches



Not suited, why?

- The scarcity of abnormal events makes **normal vs abnormal classes unbalanced**
- The result is **unreliable for defective samples** that are not sampled from one of the defective classes considered during training

# Approaches

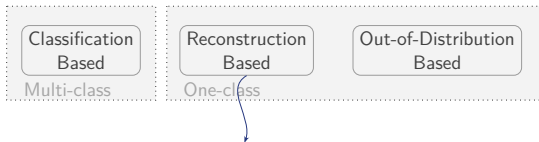


# Approaches



Project the sample onto the normal space and compare the input it with its projection.

# Approaches



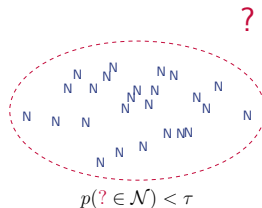
Project the sample onto the normal space and compare the input it with its ~~projection~~.

reconstruction.

Difficult, why?

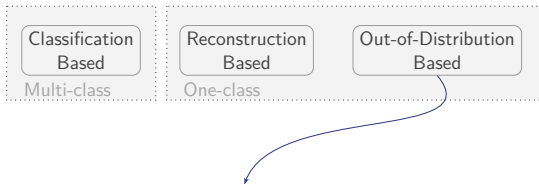
- Restrict the reconstruction to lie onto normal space exclusively
- Fix the rejection threshold

# Approaches





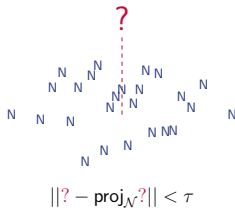
# Approaches



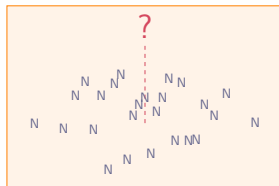
Difficult, why?

- Characterize the distribution of the normal class
- Fix the rejection threshold

# Our Method

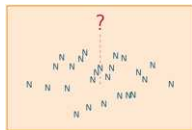


# Reconstruct a clean image



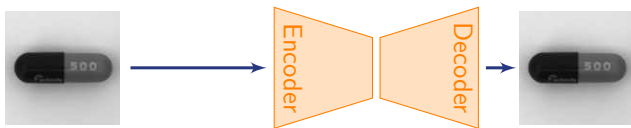
$$\|? - \text{proj}_{\mathcal{N}}?\| < \tau$$

# Reconstruct a clean image (1)

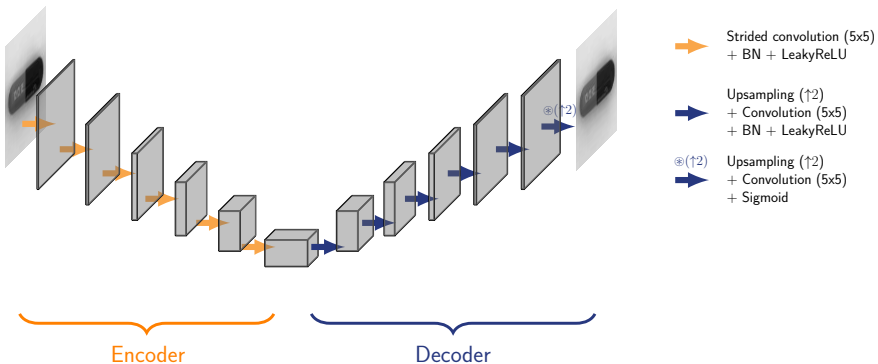


Model 1 (Baseline) :

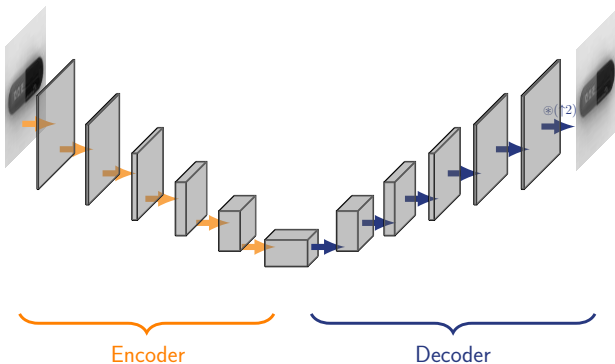
Train an **Autoencoder (AE)** to perform an identity mapping  
→ Only clean images in the training set



# Architecture of the autoencoder (AE)



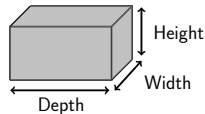
# Architecture of the autoencoder (AE)



→ Strided convolution (5x5)  
+ BN + LeakyReLU

→ Upsampling ( $\uparrow 2$ )  
+ Convolution (5x5)  
+ BN + LeakyReLU

$\otimes$  ( $\uparrow 2$ ) Upsampling ( $\uparrow 2$ )  
+ Convolution (5x5)  
+ Sigmoid



# Convolutional layer

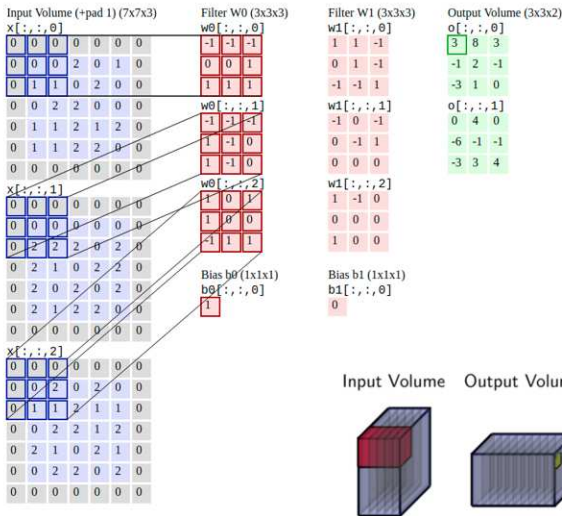


Image source CS231n: Convolutional Neural Networks for Visual Recognition 2020, Fei-Fei Li and Andrej Karpathy and Justin Johnson, <http://cs231n.stanford.edu/>

# Convolutional layer

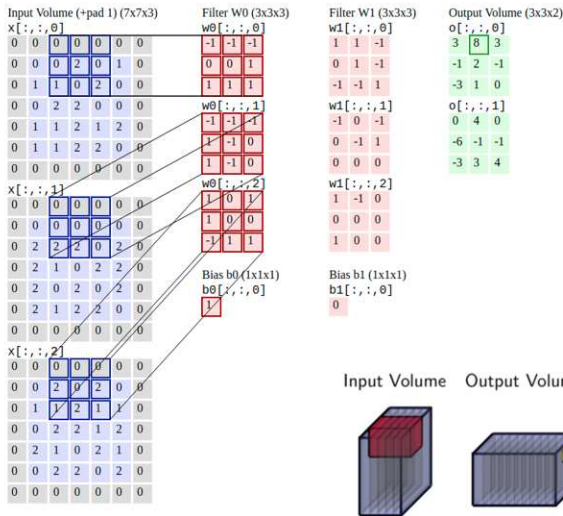


Image source CS231n: Convolutional Neural Networks for Visual Recognition 2020, Fei-Fei Li and Andrej Karpathy and Justin Johnson, <http://cs231n.stanford.edu/>



# Convolutional layer

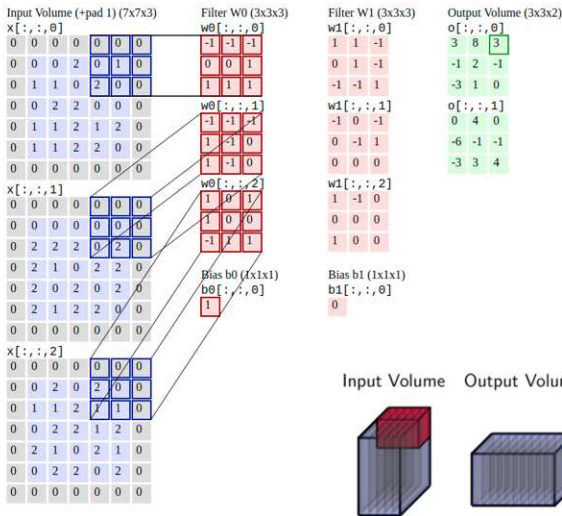


Image source CS231n: Convolutional Neural Networks for Visual Recognition 2020, Fei-Fei Li and Andrej Karpathy and Justin Johnson, <http://cs231n.stanford.edu/>

# Convolutional layer

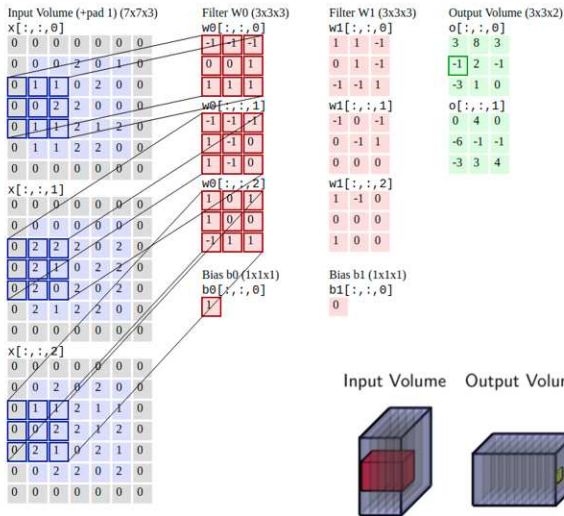


Image source CS231n: Convolutional Neural Networks for Visual Recognition 2020, Fei-Fei Li and Andrej Karpathy and Justin Johnson, <http://cs231n.stanford.edu/>

# Convolutional layer

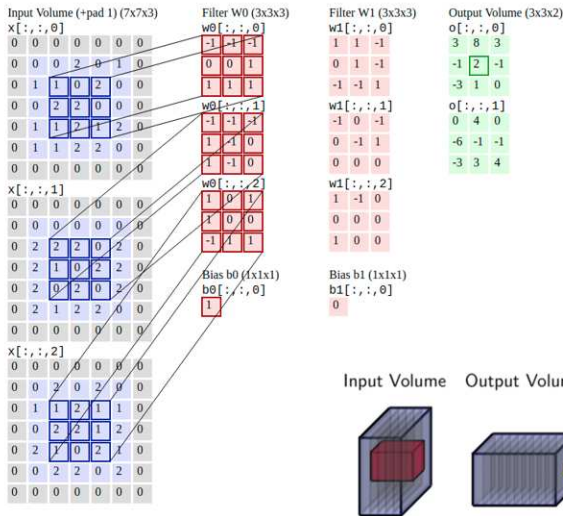


Image source CS231n: Convolutional Neural Networks for Visual Recognition 2020, Fei-Fei Li and Andrej Karpathy and Justin Johnson, <http://cs231n.stanford.edu/>

# Convolutional layer

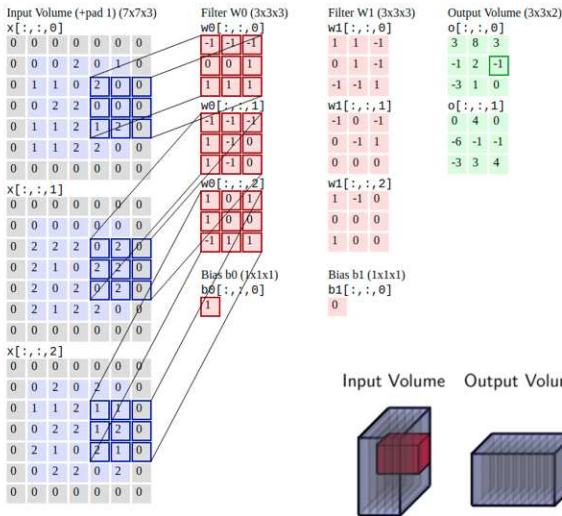


Image source CS231n: Convolutional Neural Networks for Visual Recognition 2020, Fei-Fei Li and Andrej Karpathy and Justin Johnson, <http://cs231n.stanford.edu/>

# Convolutional layer

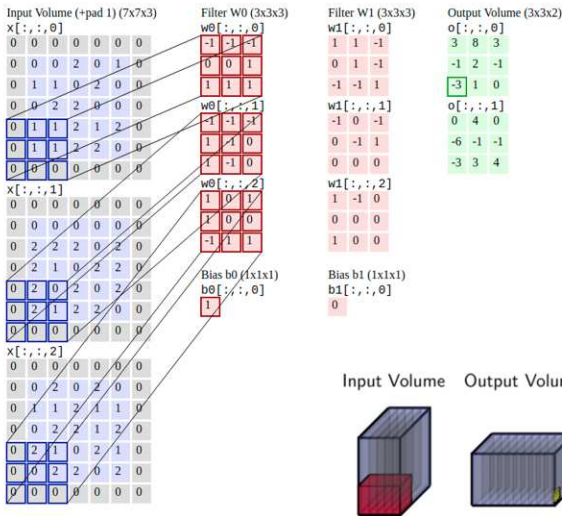


Image source CS231n: Convolutional Neural Networks for Visual Recognition 2020, Fei-Fei Li and Andrej Karpathy and Justin Johnson, <http://cs231n.stanford.edu/>

# Convolutional layer

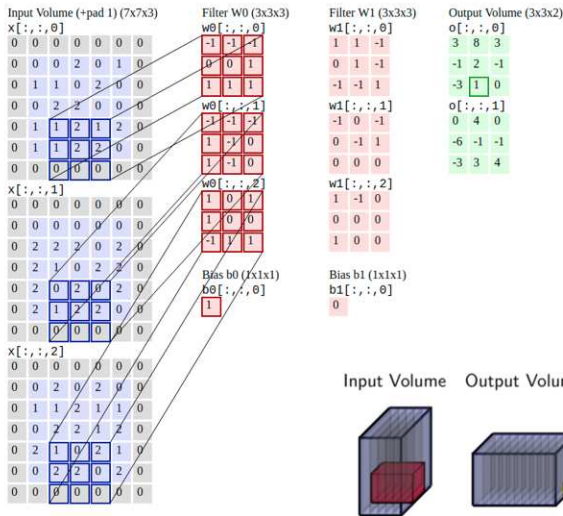


Image source CS231n: Convolutional Neural Networks for Visual Recognition 2020, Fei-Fei Li and Andrej Karpathy and Justin Johnson, <http://cs231n.stanford.edu/>

# Convolutional layer

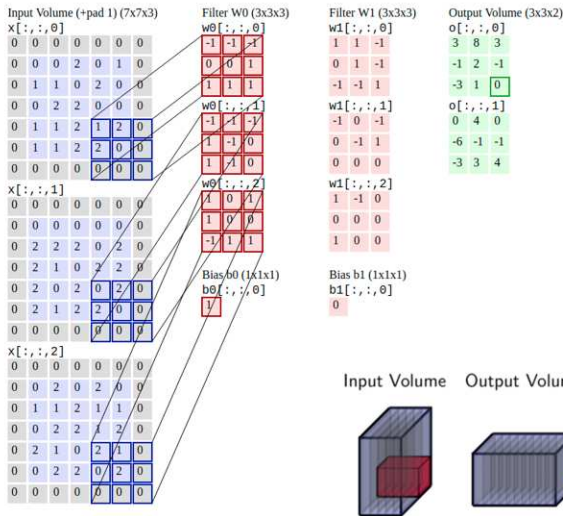


Image source CS231n: Convolutional Neural Networks for Visual Recognition 2020, Fei-Fei Li and Andrej Karpathy and Justin Johnson, <http://cs231n.stanford.edu/>

# Convolutional layer

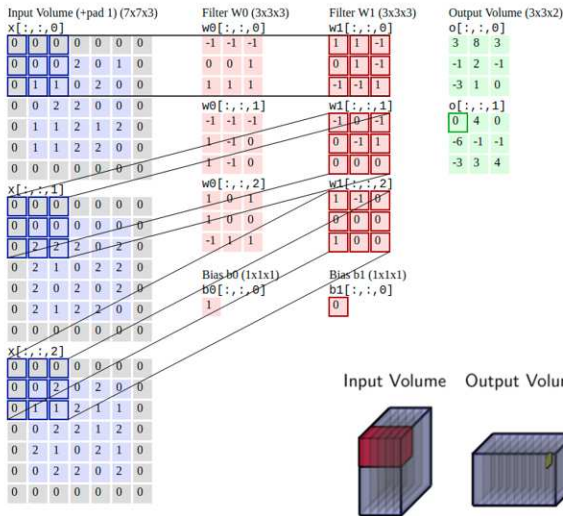


Image source CS231n: Convolutional Neural Networks for Visual Recognition 2020, Fei-Fei Li and Andrej Karpathy and Justin Johnson, <http://cs231n.stanford.edu/>



# Convolutional layer

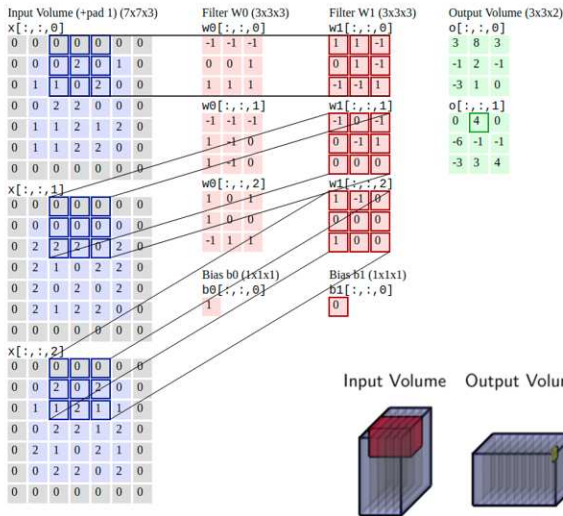


Image source CS231n: Convolutional Neural Networks for Visual Recognition 2020, Fei-Fei Li and Andrej Karpathy and Justin Johnson, <http://cs231n.stanford.edu/>

# Convolutional layer

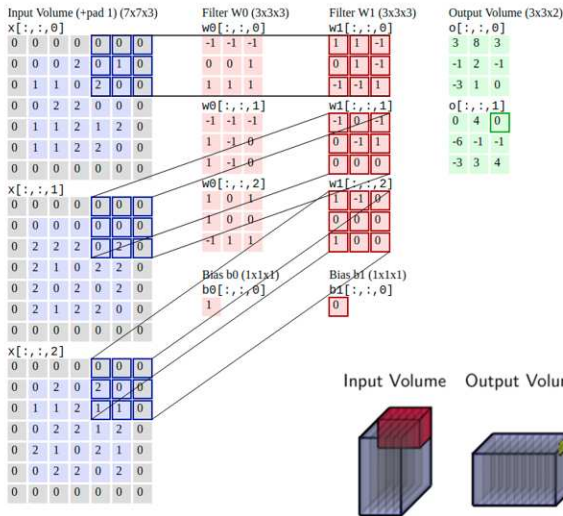


Image source CS231n: Convolutional Neural Networks for Visual Recognition 2020, Fei-Fei Li and Andrej Karpathy and Justin Johnson, <http://cs231n.stanford.edu/>

# Convolutional layer

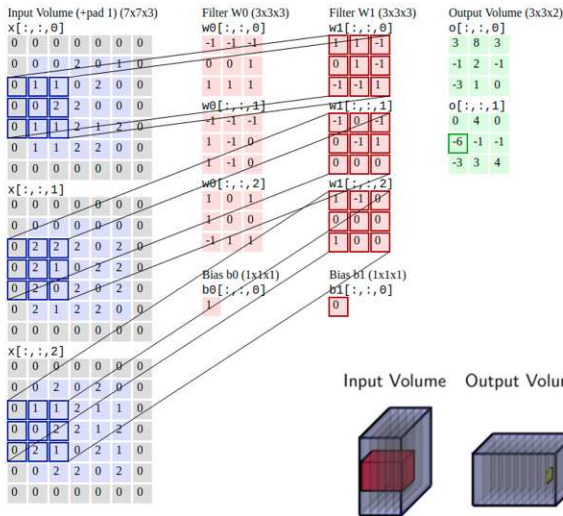


Image source CS231n: Convolutional Neural Networks for Visual Recognition 2020, Fei-Fei Li and Andrej Karpathy and Justin Johnson, <http://cs231n.stanford.edu/>

# Convolutional layer

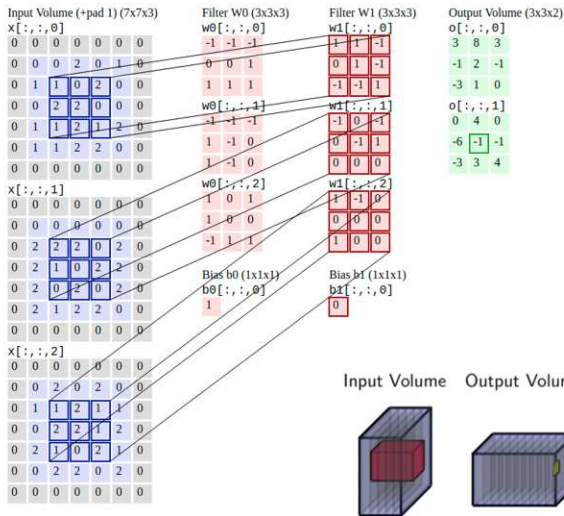


Image source CS231n: Convolutional Neural Networks for Visual Recognition 2020, Fei-Fei Li and Andrej Karpathy and Justin Johnson, <http://cs231n.stanford.edu/>

# Convolutional layer

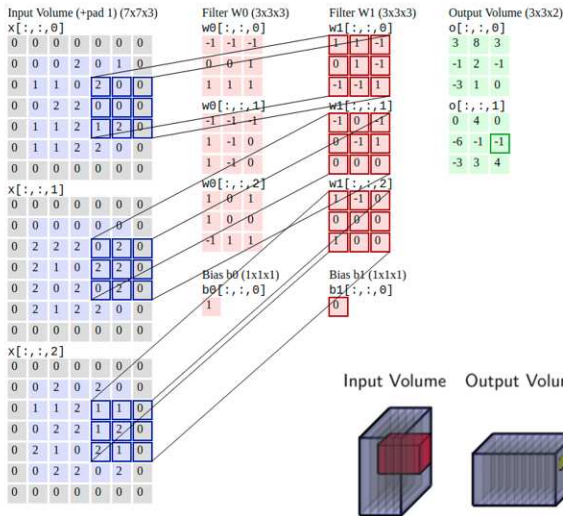


Image source CS231n: Convolutional Neural Networks for Visual Recognition 2020, Fei-Fei Li and Andrej Karpathy and Justin Johnson, <http://cs231n.stanford.edu/>

# Convolutional layer

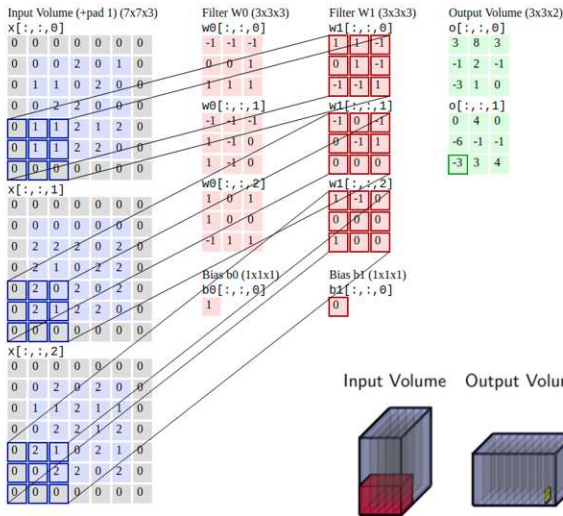


Image source CS231n: Convolutional Neural Networks for Visual Recognition 2020, Fei-Fei Li and Andrej Karpathy and Justin Johnson, <http://cs231n.stanford.edu/>

# Convolutional layer

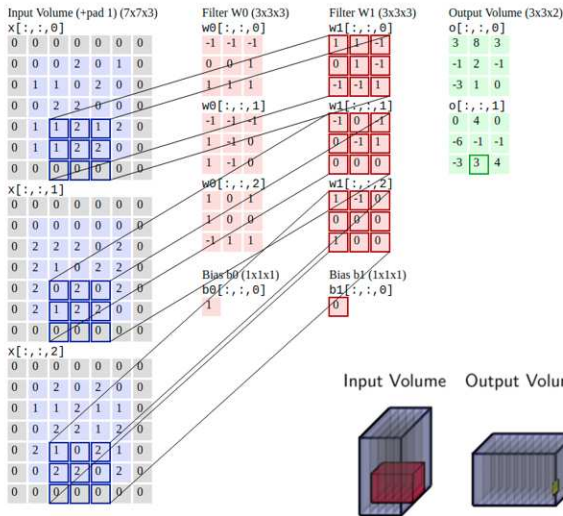


Image source CS231n: Convolutional Neural Networks for Visual Recognition 2020, Fei-Fei Li and Andrej Karpathy and Justin Johnson, <http://cs231n.stanford.edu/>

# Convolutional layer

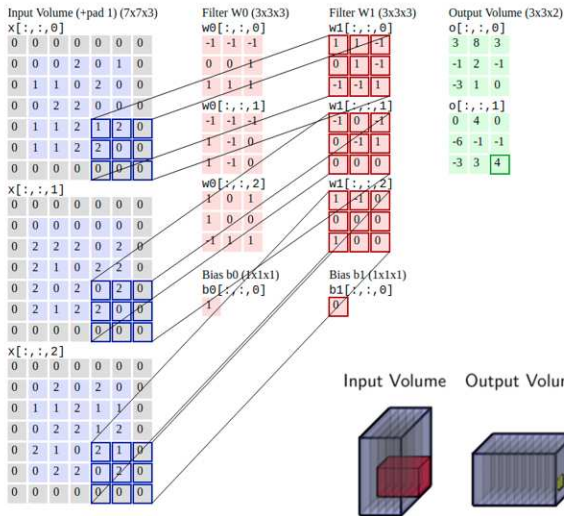
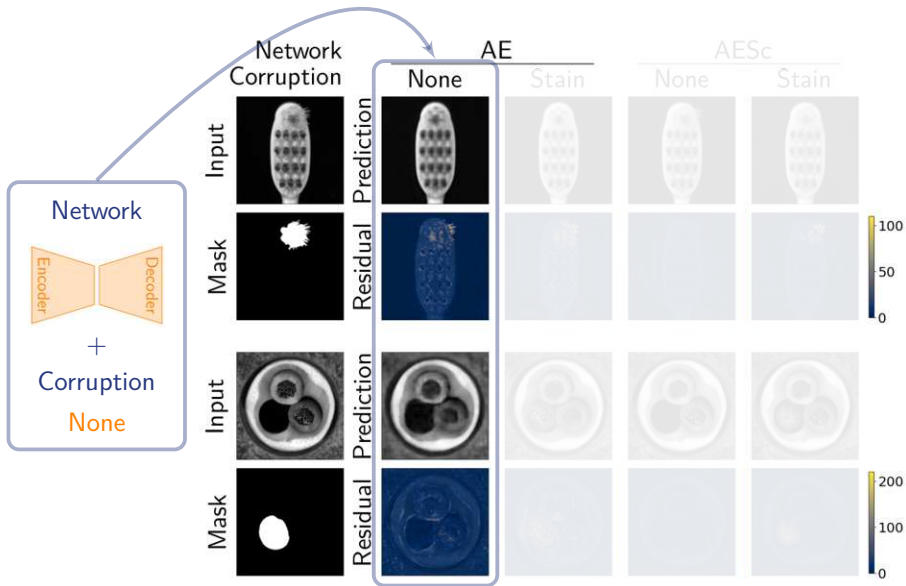
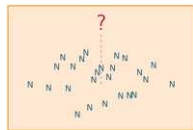


Image source CS231n: Convolutional Neural Networks for Visual Recognition 2020, Fei-Fei Li and Andrej Karpathy and Justin Johnson, <http://cs231n.stanford.edu/>



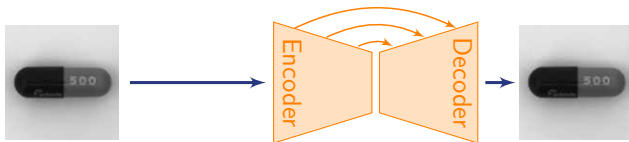


## Reconstruct a clean image (2)

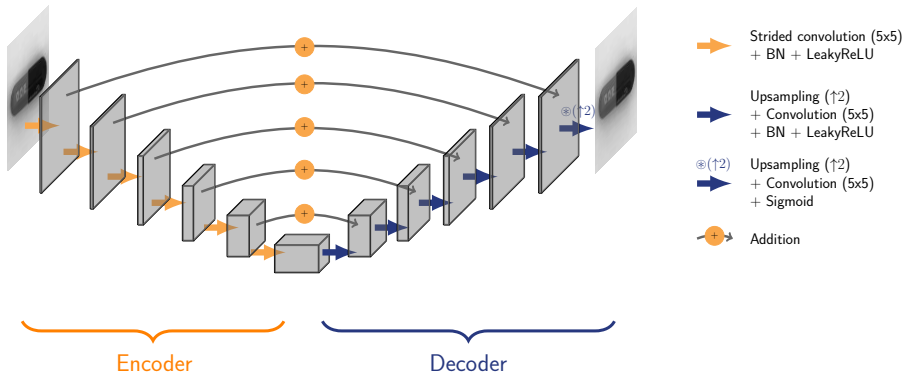


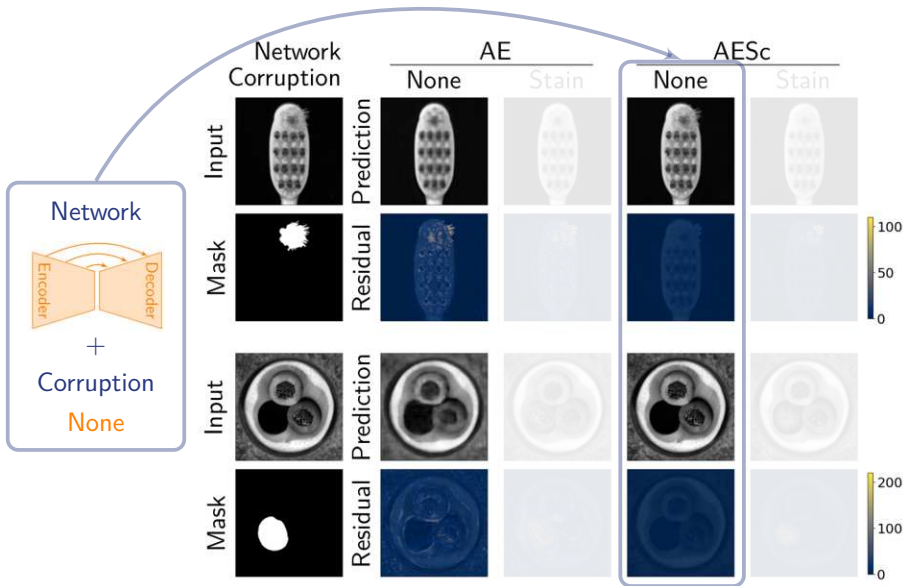
Model 2 :

Train an **Autoencoder with Skip connection (AESc)** to perform an identity mapping

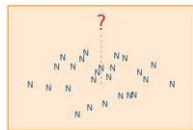


# Architecture of the autoencoder with skip connections (AESc)

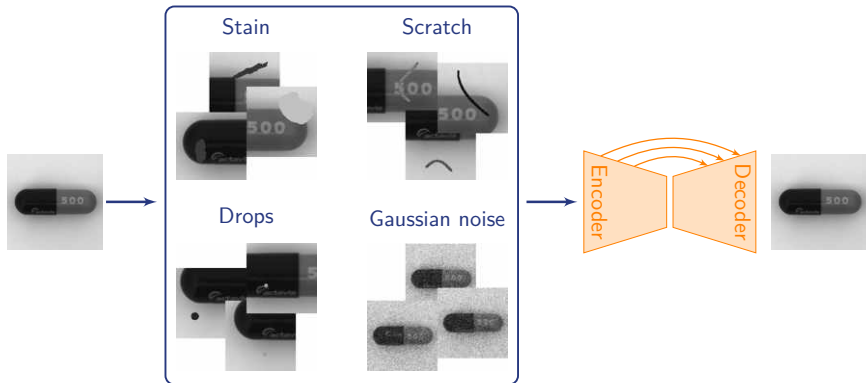


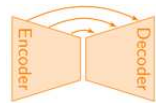


# Reconstruct a clean image (3)

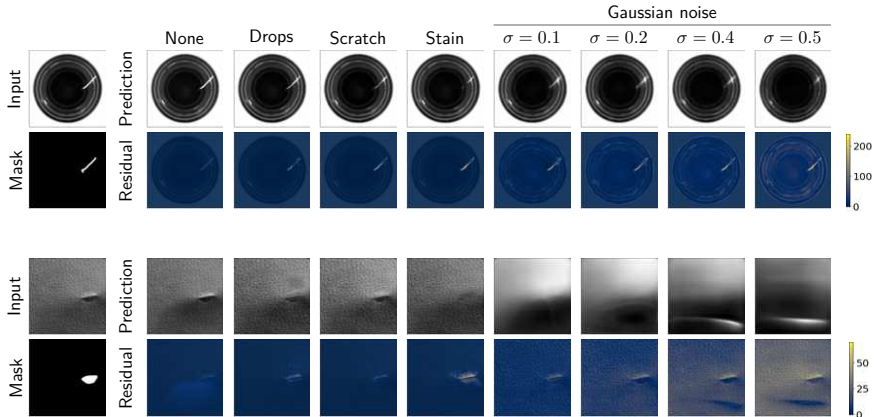


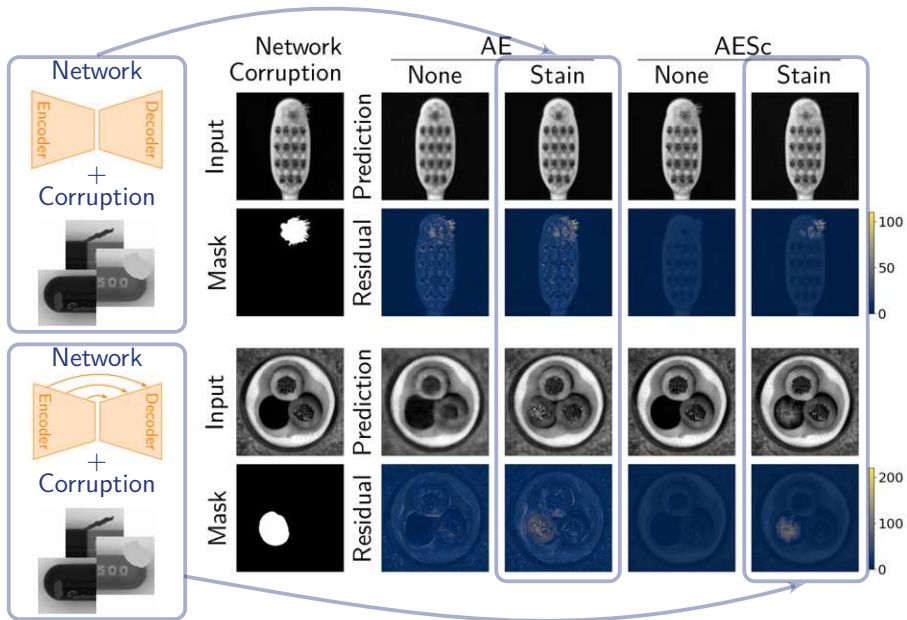
Corrupt training images with **synthetic noise** to improve the reconstruction



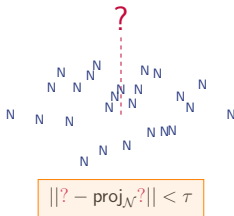


# Comparison of the corruption models





# Detect anomalies

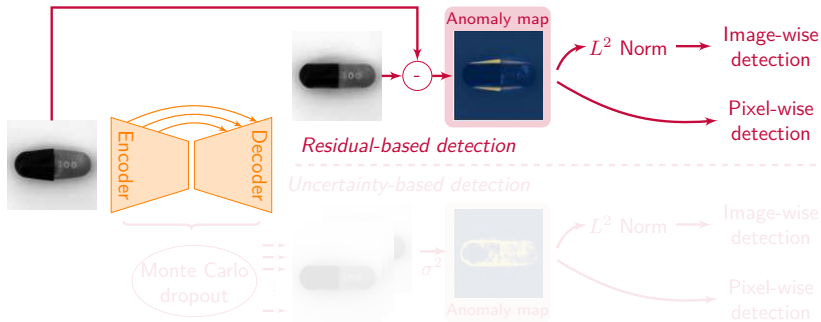


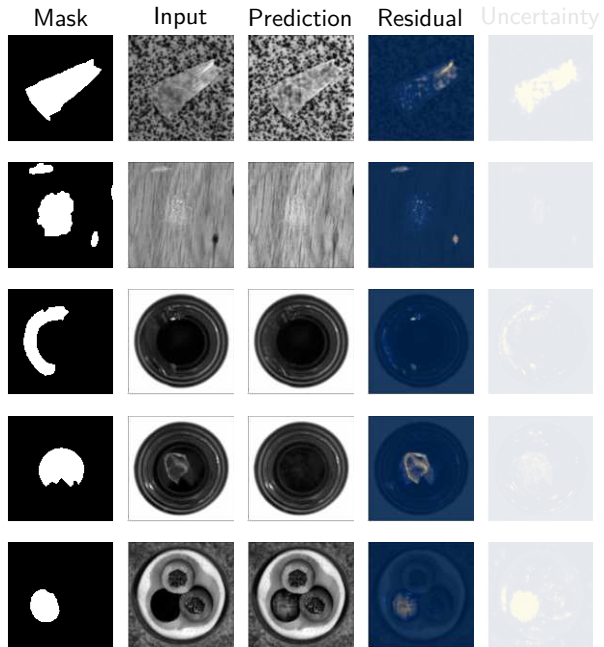


$$\|? - \text{proj}_V?\| < \tau$$

# Residual-based approach

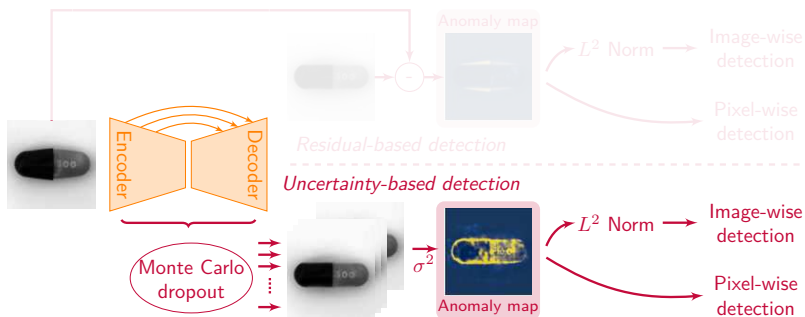
Hypothesis: Residual correlates with defective areas





## Uncertainty-based approach

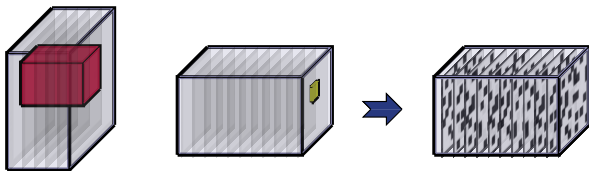
**Hypothesis:** Uncertainty correlates with structural deviations from a normal training set



# Monte Carlo Dropout

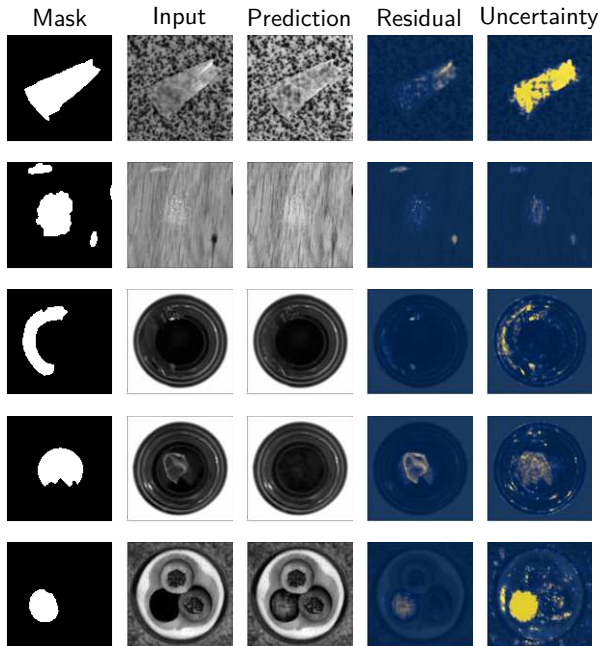
## Dropout

Randomly set values to 0

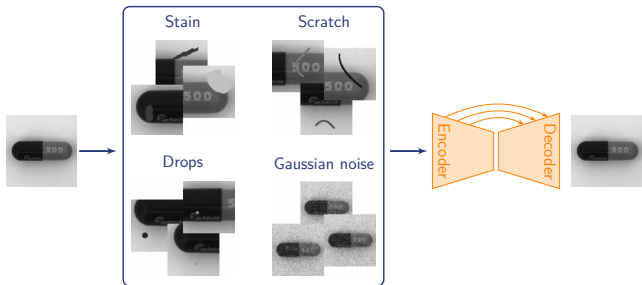


## Monte Carlo Dropout

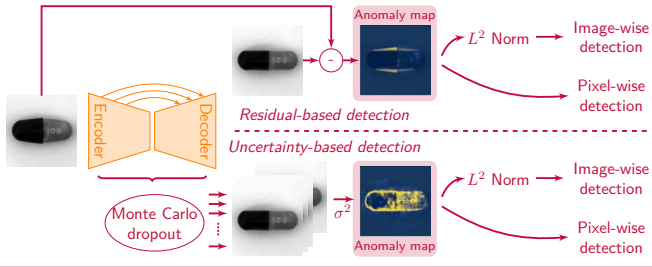
Run multiple forward passes through the model with a different dropout mask every time



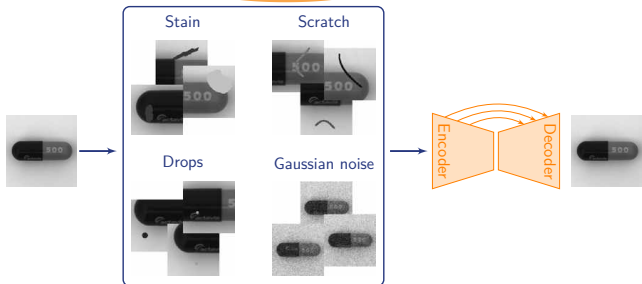
## 1. Train on clean images with synthetic corruption



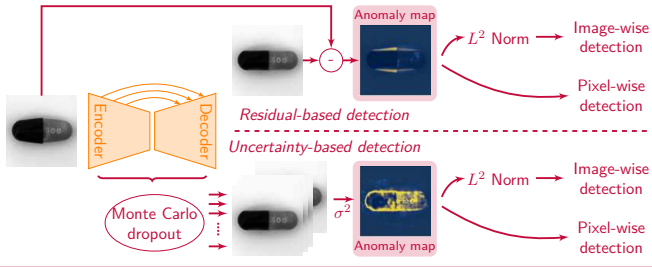
## 2. Test on arbitrary images, i.e. with or without real defect



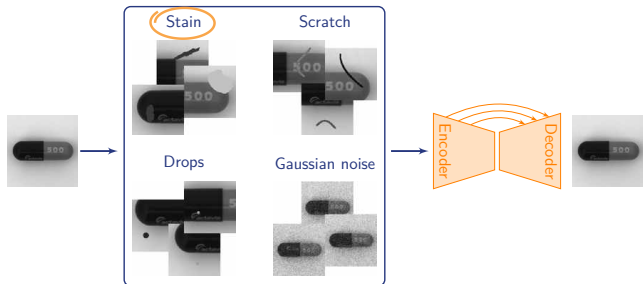
## 1. Train on clean images with synthetic corruption



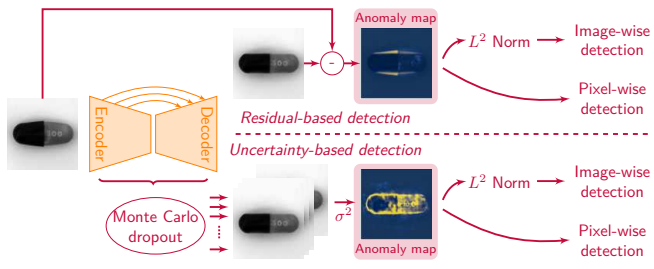
## 2. Test on arbitrary images, i.e. with or without real defect



## 1. Train on clean images with synthetic corruption

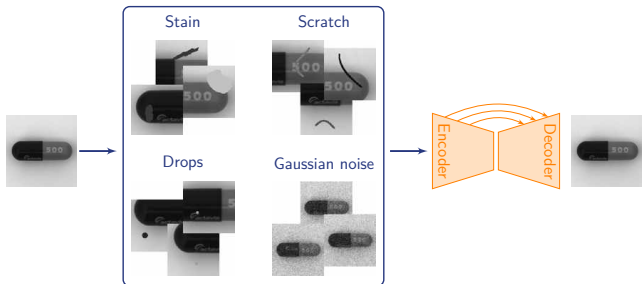


## 2. Test on arbitrary images, i.e. with or without real defect

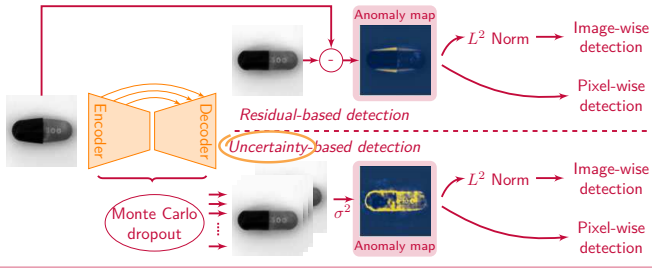




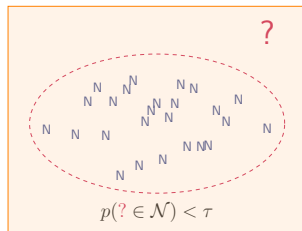
## 1. Train on clean images with synthetic corruption

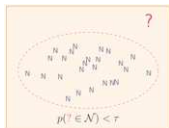


## 2. Test on arbitrary images, i.e. with or without real defect



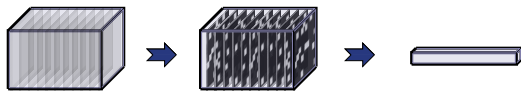
# Perspectives





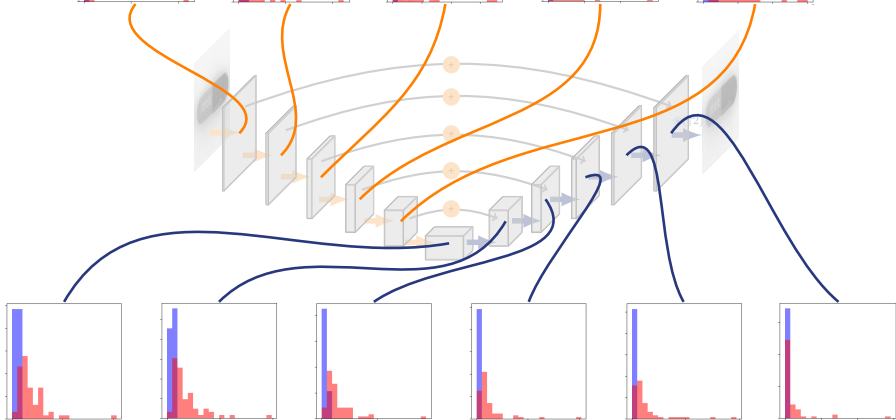
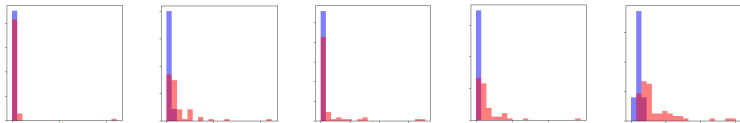
## Interesting preliminary experiment...

For each image, construct  $1 \times 64$  vectors by sampling randomly activation maps  
→ 1 mask/layer



- 1- Characterize the **clean distribution** with a Gaussian distribution (training images)
- 2- Compute the **distance** between new images and the clean distribution (test images)

Encoding

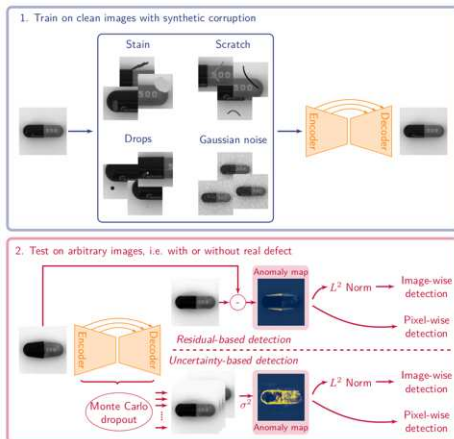


Decoding



# Synthetic corruption of images for anomaly detection using autoencoders

[ISPG SEMINAR]



Any question?

